FUEL CONSUMPTION ANALYSIS AND PREDICTION FOR HEAVY VEHICLES

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Abstract_Compared to the previous way of measuring fuel consumption based on the time period, machine learning models are useful for calculating fuel consumption depending on the distance travelled. This methodology is combined with seven predictors based on road grade and vehicle speed to create a highly predictive neural network model for heavy vehicle average fuel consumption. This tactic is used in conjunction with the following metrics: average moving speed, characteristic acceleration, aerodynamic speed squared, number of stops, stops time, change in kinetic energy, and change in potential energy. It produces a highly predictive neural network model for heavy vehicle fuel consumption on average. For each specific car, it is easy to create and implement in order to maximise fuel consumption.

1.INTRODUCTION

Producers, controllers, and clients are undeniably keen on vehicle fuel utilization models. They are expected during all phases of the vehicle's life cycle. We will demonstrate run of the mill fuel use for weighty vehicles during activity and upkeep in this task. Physical science based models, AI models, and factual models are the classifications three essential of build approaches used to fuel

utilization models. There have been a few past models created for both prompt and normal fuel use. Since they can address the elements of the framework's action at different time steps, material science based models are the most ideal for assessing momentary fuel utilization. The proposed framework relies upon 7 elements to anticipate the typical fuel utilization. Seven factors, for example, time-halted. num-stops, normal

moving-speed, trademark speed increase, streamlined speed-squared, change-in-motor energy, change-inpotential-energy are recorded from every vehicle head out as much as 100 kilo meters like number of times vehicles halted, complete halted time taken and so on. This multitude of values are gathered from weighty vehicle and use as dataset to prepare ANN model.

2.LITERAATURE SURVEY

2.1.NEURAL NETWORK-BASED PREDICTION OF VEHICLE FUEL CONSUMPTION BASED ON DRIVING CYCLE DATA:

URL:<u>https://www.researchgate.net/pub</u> lication/357744098 Neural NetworkB ased Prediction of Vehicle F uel Consumption Based on Driving Cycle Data

This paper deals with fuel consumption prediction based on vehicle velocity, acceleration, and road slope time series inputs. Several datadriven models are considered for this purpose, including linear regression models and neural network-based ones. The emphasis is on accounting for the road slope impact when forming the model inputs, in order to improve the

prediction accuracy. A particular focus is devoted to conversion of lengthvarying driving cycles into fixed dimension inputs suitable for neural networks. The proposed prediction parameterized algorithms are and tested based on GPS- and CAN based tracking data recorded on a number of buses during the irregular city operation. The test results demonstrate that a proposed neural network-based approach provides a favorable prediction accuracy and reasonable execution speed, thus making it suitable for various applications such vehicle routing optimization, as synthetic driving cycle validation, transport planning and similar.

2.2. AN ENHANCED FUEL CONSUMPTION MACHINE LEARNING MODEL IN VEHICLES:

URL:

https://ui.adsabs.harvard.edu/abs/2021J PhCS1979a2068D/abstract

In the present world, some of the people are not able to pay expenses for petrol/diesel. The model which we are generating will be useful for many people. The system which we are generating is a data summary approach will be based on distance rather than traditional conventional time period when developing personalized machine learning model for fuel consumption. utilized This system is within conjunction with vehicle pace Also seven predictors inferred starting with way review to prepare a neural system model utilizing machine Taking in that predicts Normal fuel utilization done vehicles. Different window sizes are evaluated and the results mean that the 1km window can estimate the fuel consumption with a coefficient of 0.91 and it also means less than 4% peak to peak percentage error for routes that include both city and highway duty cycling sections.

2.3. FUEL CONSUMPTION PREDICTION MODEL USING MACHINELEARNING:

URL:<u>https://www.researchgate.net/pub</u> lication/356819804_Fuel_Consumptio <u>n_Prediction_Model_using___Machine</u> Learning

In the paper, we are enhancing the accuracy of the fuel consumption prediction model with Machine Learning to minimize Fuel Consumption. This will lead to an economic improvement for thebusiness

and satisfy the domain needs. We propose a machine learning model to predict vehicle fuel consumption. The proposed model is based on the Support Vector Machine algorithm. The Fuel Consumption estimation is given as a function of Mass Air Flow, Vehicle Speed, Revolutions per Minute, and Throttle Position Sensor features. Our model can compete with other Machine Learning algorithms for the same purpose which will help manufacturers find more choices for successful Fuel Consumption Prediction models.

3.PROPOSED SYSTEM

The average fuel usage is predicted by the proposed approach based on seven factors. Seven variables are recorded from each vehicle travel up to 100 kilometres, including the number of stops, total time spent stopped, characteristic acceleration, aerodynamic speed squared, number of stops, change in kinetic energy, and change in potential energy. These values are all gathered from heavy vehicles and used as training data for artificial neural networks.

In this study, fuel consumption throughout the distance traveled within the same time period is the output,

Read Dataset &

while the input is aggregated in the time domain at 10-minute intervals. A transfer function F(p) = 0, where $F(\cdot)$ denotes the system, p stands for the input predictors, and o denotes the system's response or output, is used to depict the complex system. Feed Forward Neural Networks (FNN) are the type of ANNs used in this paper. Training is an iterative process that can be carried out with a variety of methods, such as back propagation and particle swarm optimization. Future research will examine alternative strategies to see if they may raise the predicted accuracy of the model.

3.1 IMPLEMENTATION

• Upload Heavy Vehicles Fuel Dataset: Using this module we can upload train dataset to application. Dataset contains comma separated values. Generate Model: We'll use this module to read a comma-separated dataset and then create a train and test model for an ANN using the values from that dataset. The dataset will be separated into two sections, with 80 percent being used to train the ANN modeland 20 percent being used to test it. Run

ANN

Algorithm: Using this model, we can create ANN object and then feed train and test data to build ANN model.

• Predict Average Fuel Consumption: We will upload new test data to this module, and ANN will apply a train model to that data in order to predict average fuel usage for those test records.



Fig 1:Architecture

4.RESULTS AND DISCUSSION

4 Average Fuel Consumption	
Prediction and Analysis of Fuel Consumption in Heavy Vehicles	
	Upload Heavy Vehicles Fuel Dataset
C:/Users/Administrator/Downloads/Fuel_Dataset.csv loaded	
Dataset Length:702 Splitted Training Length:561 Splitted Test Length:141 ANN Accuracy for dataset C:/Users/Administrator/Downloads/Fuel_Dataset.csv Accuracy Spore:87 2340440750122	Read Dataset & Generate Model
	Run ANN Algorithm
	Predict Average Fuel Consumption
	Fuel Consumption Graph
	Exit

fig-2: Running the ANN algorithm and displaying the accuracy

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113/113 - US - LOSS: U.3U31 - ACCURACY: U.8045 - 150MS/0000 - 1MS/STOP Enoch 190/200
113/113 - 0s - loss: 0.3412 - accuracy: 0.8556 - 156ms/epoch - 1ms/step
Epoch 191/200
113/113 - 0s - loss: 0.3740 - accuracy: 0.8307 - 15óms/epoch - 1ms/step
Epoch 192/200
113/113 - Os - loss: 0.3267 - accuracy: 0.8592 - 156ms/epoch - 1ms/step
Epoch 193/200
113/113 - Os - loss: 0.2760 - accuracy: 0.8841 - 172ms/epoch - 2ms/step
Epoch 194/200
113/113 - Os - loss: 0.2748 - accuracy: 0.8806 - 156ms/epoch - 1ms/step
Epoch 195/200
113/113 - Os - loss: 0.2685 - accuracy: 0.8806 - 156ms/epoch - 1ms/step
Epoch 196/200
113/113 - Os - loss: 0.3714 - accuracy: 0.8307 - 15óms/epoch - 1ms/step
Epoch 197/200
113/113 - Os - loss: 0.2995 - accuracy: 0.8610 - 156ms/epoch - 1ms/step
Epoch 198/200
113/113 - 0s - loss: 0.2529 - accuracy: 0.8877 - 15óms/epoch - 1ms/step
Epoch 199/200
113/113 - 0s - loss: 0.3187 - accuracy: 0.8449 - 15óms/epoch - 1ms/step
Epoch 200/200
113/113 - 0s - loss: 0.2904 - accuracy: 0.8574 - 15óms/epoch - 1ms/step
5/5 [=============================] - 0s 0s/step - loss: 0.5144 - accuracy: 0.8723

fig-3: Running ANN algorithm



fig-4: To predict the data, on clicking predict average fuel consumption button it will prompt to upload the test data set. After that it displays the predicted data corresponding to test data set



fig-5: displaying the fuel consumption graph

5.CONCLUSION

A convenient machine learning model that can be created for every heavy vehicle in a fleet. The number of stops, duration of stops, average speed, characteristic acceleration, squared aerodynamic speed, change in kinetic energy, and change in potential energy are the seven predictors that the model uses.In order to better capture the average dynamic behavior of the vehicle, the final two predictors are presented in this research. The road gradient and vehicle speed are the model's primary predictors.Telemetric devices, which are becoming a standard component of linked cars, easily provide these values. Furthermore, these two variables make it simple to compute the predictors onboard.

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